

# Specifications Required of SeaSonde Products That Dictate Operating Frequency Band and Transmit Power

- A. Signal-to-Noise ratio must exceed 13 dB for surface current extraction from the radar echo**
- B. Maximum range must reach**
  - 1) 200 km for Long-Range Coastal SeaSonde System**
  - 2) 75 km for Low-Band Standard Coastal SeaSonde**
  - 3) 40 km for Mid-Band Standard Coastal SeaSonde**
  - 4) 15 km for High-Band High-Resolution Harbor SeaSonde**

## Signal-to-Noise Ratio Dependence on Radar and Environmental Parameters -- And Definitions

$$S/N = \frac{P_t G_t L_c D_r F^4 \sigma A^2}{(4\pi R)^3 kT F_a}$$

<b>S/N</b>	Signal-to-Noise ratio
<b>P<sub>t</sub></b>	Transmitter output power (average) -- SeaSonde duty factors are always 50%
<b>G<sub>t</sub></b>	Transmit antenna power-gain over earth, including ground losses
<b>L<sub>c</sub></b>	Cable losses to transmit antenna
<b>D<sub>r</sub></b>	Receive antenna directive gain, excluding ground losses (external noise always dominates receive antenna losses and noise figure in SeaSondes)
<b>F</b>	One-way attenuation factor above normal free-space spreading loss experienced by surface wave above lossy spherical earth, raised to fourth power to include two-way radar path for signal power. Calculated from standard computer codes developed at Department of Commerce Institute for Telecommunications Science, [Berry & Chrisman, 1965] based on theory of J. Wait [ <i>Electromagnetic Waves in Stratified Media</i> , Pergamon Press, 1962], and including effects of sea state roughness [Barrick, D. E., <i>Radio Science</i> , 1971, pp. 517-533]
<b>R</b>	Range to radar scattering cell at maximum specified distance

- Normalized radar cross section of first-order Bragg scatter from sea at HF, taken from theory and experiments [D. E. Barrick, *IEEE Transactions on Antennas & Propagation*, 1972, pp. 2-10]
- A** Area inside radar cell at maximum specified range:  $= R^2 \theta$ , where R is maximum specified range;  $\theta$  is the radar cell size (determined from signal bandwidth); and  $\theta$  is the azimuth (bearing) angular width, which for SeaSonde is always 5°  
  
Radar wavelength:  $= 300/f_{\text{MHz}}$  (meters)
- i** Integration time or FFT time-series length (in seconds) for spectral processing; this is  $1/B$ , where B is the effective noise bandwidth of the system
- kT** Internal receiver front-end noise per unit bandwidth at room temperature, where  $T = 270^\circ\text{K}$ , and  $k = \text{Boltzmann's constant} = 1.38 \times 10^{-23}$
- F<sub>a</sub>** Factor by which external noise at HF exceeds internal noise; obtained from *C.C.I.R. Report No. 322*, International Telecommunications Union, Geneva, 1964. An average value for this factor across the HF band (in dB) is calculated from the following formula that is fitted to the C.C.I.R. data:

$$F_a = 70 - 27.5 \text{ Log}_{10}(f_{\text{MHz}})$$

# Spreadsheet Calculations Supporting Required Power and Operating Frequency for Four Specified SeaSonde Ranges

- Add **red dB numbers in second columns** to get S/N ratio at bottom;
- Numbers for dB in denominator of equation are shown in parentheses, with appropriate minus signs so all numbers in columns can be added;
- Frequency is rounded to nearest MHz. That is, 5 MHz represents operation in band 4.7-5.2 MHz; 13 MHz represents operation between 12 - 14 MHz; 25 MHz represents 24-27 MHz; and 42 MHz represents 40-45 MHz.

Frequency (MHz)	5	13	25	42
$P_t$	50 w	50 w	50 w	25 w
$G_t$	1.0	1.0	1.6	1.6
$L_c$				
$D_r$	3.2	3.2	3.2	3.2
$F_o$				
$R$	3 km	2 km	1 km	200 m
$R$	200 km	75 km	40 km	16 km
$A$				
$R^{-4}$				
$2$				
$(4)^{-3}$				
$(kT)^{-1}$				
$i$	1024 s	256 s	256 s	128 s
$(F_a)^{-1}$				
<b>S/N</b>	<b>13.3 dB</b>	<b>14.3 dB</b>	<b>13.5 dB</b>	<b>13.9 dB</b>